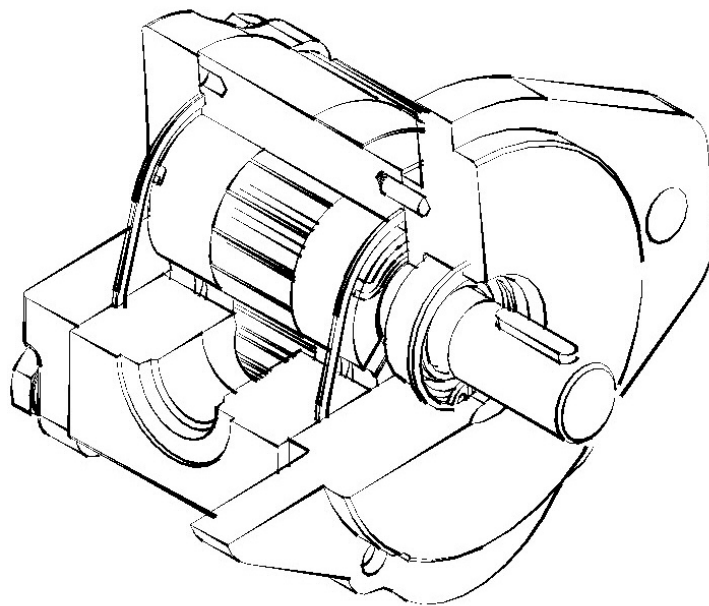


**Displacement** from 2 to 15 ccm  
**Pressure** up to 280 bar  
**Speed** from 500 to 4000 RPM

**GEAR MOTORS**  
**JM**

## TABLE OF CONTENTS

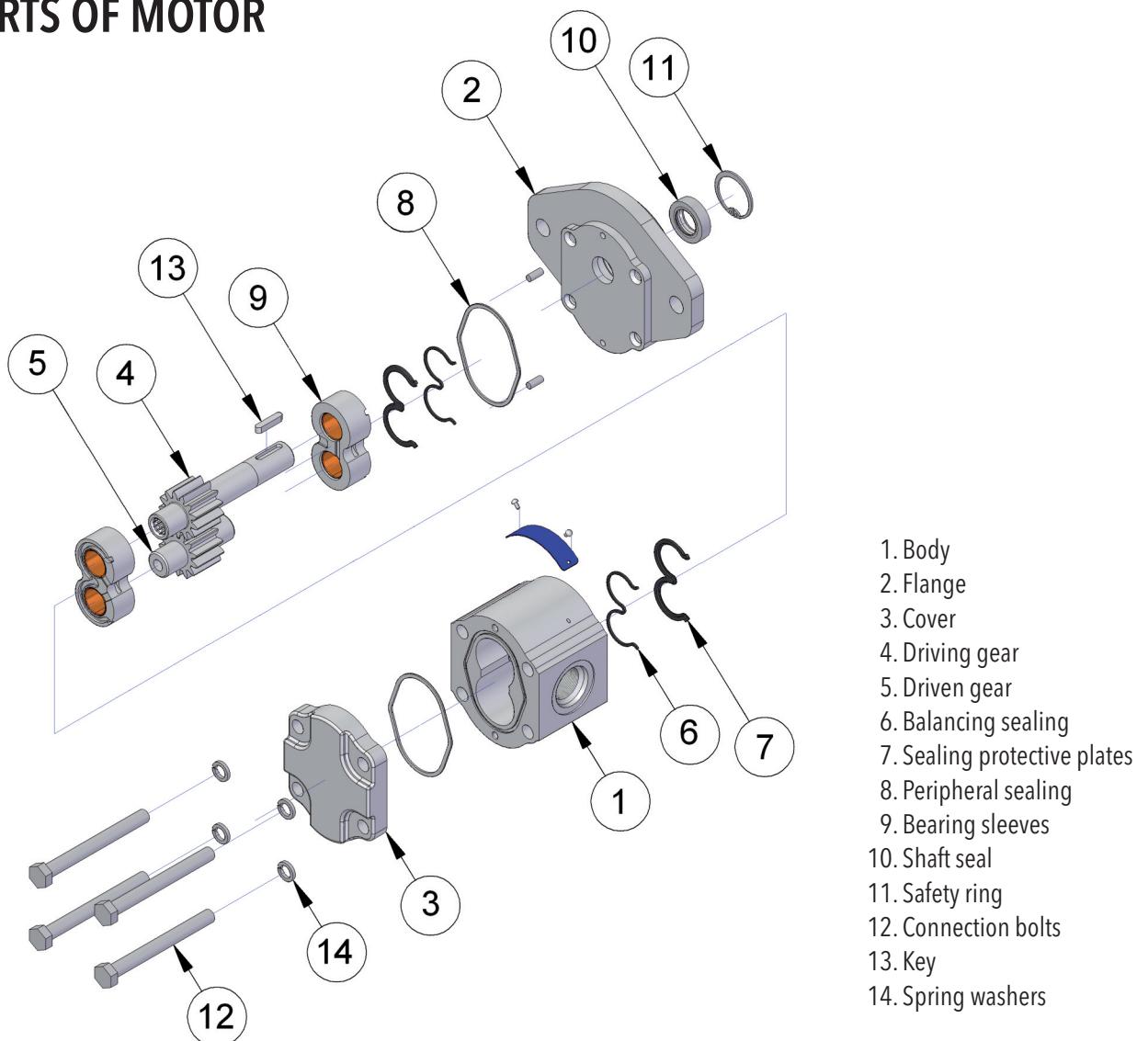
DESCRIPTION.....	2
BASIC PARTS OF MOTOR.....	2
PARAMETER TABLE.....	3
FORMULAS USED FOR CALCULATION.....	5
MOTOR EFFICIENCIES.....	5
WORKING LIQUID.....	6
PRESSURE LOAD.....	6
DIRECTION OF ROTATION.....	7
REVERSIBLE DESIGN.....	7
JM FLOW RATE AND POWER CURVES.....	8
ORDER KEY.....	11
COMBINATIONS OF FLANGES AND SHAFTS.....	12
FLANGES DESIGN.....	13
DRIVE SHAFTS.....	14
LIQUID INLET AND OUTLET CONNECTION.....	16
CATALOGUE SHETS OF JM SERIES BASIC DESIGNS.....	17
NOTES.....	21



## DESCRIPTION

- Gear motors are used for transformation of liquid pressure head in mechanical energy. The JM line motors are designed for advanced hydraulic systems with lower capacity (approximately up to 10 kW) with high operational reliability and long service life. A wide variety of designs with diverse drives, connecting flanges, fluid inlets and outlets enable the motors to be used in hydraulic systems of both fixed and mobile machines and equipment. The JM series covers the range of displacements from 2 to 15 cm<sup>3</sup>/rev.
- The flange types used as well as the form of the working liquid inlets and outlets (located laterally – in the body or axially – in the cover) meet all worldwide standards. The pump body is made of a heavy duty aluminium alloy. The cover and the flange are made of grey iron or aluminium alloy, and gear wheels of heavy duty steel. Axle pins with a high surface duality are imbedded in sliding sleeves, continuously lubricated and cooled by a stream of working liquid. JM line motors can be delivered in one-way design as clockwise or anti-clockwise rotating engines; they are also available in reversible version.

## BASIC PARTS OF MOTOR



1. Body
2. Flange
3. Cover
4. Driving gear
5. Driven gear
6. Balancing sealing
7. Sealing protective plates
8. Peripheral sealing
9. Bearing sleeves
10. Shaft seal
11. Safety ring
12. Connection bolts
13. Key
14. Spring washers

## PARAMETER TABLE

### One direction motors

Nominal Size Parameters		Sym.	Unit	JM 2	JM 3	JM 4	JM 5	JM 6	JM 7
Actual displacement		$V_g$	[cm <sup>3</sup> ]	2.00	3.01	4.01	5.01	6.02	7.02
Rotation speed	nominal	$n_n$	[min <sup>-1</sup> ]	1500	1500	1500	1500	1500	1500
	minimum	$n_{min}$	[min <sup>-1</sup> ]	500	500	500	500	500	500
	maximum	$n_{max}$	[min <sup>-1</sup> ]	4000	4000	4000	4000	3600	3500
Pressure at outlet	minimum	$p_{1min}$	[bar]	-0.3	-0.3	-0.3	-0.3	-0.3	-0.3
	maximum	$p_{1max}$	[bar]	210	210	210	210	210	210
Pressure at inlet	max. continuous	$p_{2n}$	[bar]	280	280	280	280	280	280
	maximum	$p_{2max}$	[bar]	290	290	290	290	290	290
	peak	$p_3$	[bar]	300	300	300	300	300	300
Nominal input flow rate (max.) at $n_n$ and $p_{2n}$		$Q_n$	[dm <sup>3</sup> .min <sup>-1</sup> ]	3.54	5.31	6.84	8.55	10.03	11.70
Maximum input flow rate at $n_{max}$ and $p_{2max}$		$Q_{max}$	[dm <sup>3</sup> .min <sup>-1</sup> ]	8.55	12.81	17.08	21.34	23.04	24.64
Nominal output power (min.) at $n_n$ and $p_{2n}$		$P_n$	[kW]	1.20	1.80	2.40	3.00	3.60	4.20
Maximum output power at $n_{max}$ and $p_{2max}$		$P_{max}$	[kW]	3.28	4.92	6.56	8.20	8.86	9.47
Nominal Torque at $n_n$ and $p_{2n}$		$M$	[Nm]	7.61	11.40	15.20	19.00	22.79	26.59
Weight		$m$	[kg]	1.75	1.80	1.85	1.90	1.95	1.95

Nominal Size Parameters		Sym.	Unit	JM 8	JM 10	JM 11	JM 12	JM 15
Actual displacement		$V_g$	[cm <sup>3</sup> ]	8.02	10.03	11.03	12.03	15.01
Rotation speed	nominal	$n_n$	[min <sup>-1</sup> ]	1500	1500	1500	1500	1500
	minimum	$n_{min}$	[min <sup>-1</sup> ]	500	500	500	500	500
	maximum	$n_{max}$	[min <sup>-1</sup> ]	3100	2800	2500	2400	2200
Pressure at outlet	minimum	$p_{1min}$	[bar]	-0.3	-0.3	-0.3	-0.3	-0.3
	maximum	$p_{1max}$	[bar]	210	180	165	150	110
Pressure at inlet	max. continuous	$p_{2n}$	[bar]	280	250	235	220	190
	maximum	$p_{2max}$	[bar]	290	270	255	240	210
	peak	$p_3$	[bar]	300	280	265	250	220
Nominal input flow rate (max.) at $n_n$ and $p_{2n}$		$Q_n$	[dm <sup>3</sup> .min <sup>-1</sup> ]	13.37	16.71	18.38	20.05	25.06
Maximum input flow rate at $n_{max}$ and $p_{2max}$		$Q_{max}$	[dm <sup>3</sup> .min <sup>-1</sup> ]	25.60	29.86	28.16	30.71	35.19
Nominal output power (min.) at $n_n$ and $p_{2n}$		$P_n$	[kW]	4.80	5.30	5.48	5.60	5.72
Maximum output power at $n_{max}$ and $p_{2max}$		$P_{max}$	[kW]	9.94	10.69	9.62	9.87	9.90
Nominal Torque at $n_n$ and $p_{2n}$		$M$	[Nm]	30.38	35.06	35.80	36.62	35.06
Weight		$m$	[kg]	2.00	2.10	2.10	2.20	2.45

## Reversible motors

Nominal Size Parameters		Sym.	Unit	JM 2	JM 3	JM 4	JM 5	JM 6	JM 7
Actual displacement		$V_g$	[cm <sup>3</sup> ]	2.00	3.01	4.01	5.01	6.02	7.02
Rotation speed	nominal	$n_n$	[min <sup>-1</sup> ]	1500	1500	1500	1500	1500	1500
	minimum	$n_{min}$	[min <sup>-1</sup> ]	500	500	500	500	500	500
	maximum	$n_{max}$	[min <sup>-1</sup> ]	4000	4000	4000	4000	3600	3500
Pressure at outlet	minimum	$p_{1min}$	[bar]	-0.3	-0.3	-0.3	-0.3	-0.3	-0.3
	maximum	$p_{1max}$	[bar]	180	180	180	180	180	180
Pressure at inlet	max. continuous	$p_{2n}$	[bar]	250	250	250	250	250	250
	maximum	$p_{2max}$	[bar]	260	260	260	260	260	260
	peak	$p_3$	[bar]	270	270	270	270	270	270
Nominal input flow rate (max.) at $n_n$ and $p_{2n}$		$Q_n$	[dm <sup>3</sup> .min <sup>-1</sup> ]	3.54	5.31	6.84	8.55	10.03	11.70
Maximum input flow rate at $n_{max}$ and $p_{2max}$		$Q_{max}$	[dm <sup>3</sup> .min <sup>-1</sup> ]	8.55	12.81	17.08	21.34	23.04	24.64
Nominal output power (min.) at $n_n$ and $p_{2n}$		$P_n$	[kW]	1.20	1.80	2.40	3.00	3.60	4.20
Maximum output power at $n_{max}$ and $p_{2max}$		$P_{max}$	[kW]	3.28	4.92	6.56	8.20	8.86	9.47
Nominal Torque at $n_n$ and $p_{2n}$		$M$	[Nm]	7.61	11.40	15.20	19.00	22.79	26.59
Weight		$m$	[kg]	1.75	1.80	1.85	1.90	1.95	1.95

Nominal Size Parameters		Sym.	Unit	JM 8	JM 10	JM 11	JM 12	JM 15
Actual displacement		$V_g$	[cm <sup>3</sup> ]	8.02	10.03	11.03	12.03	15.01
Rotation speed	nominal	$n_n$	[min <sup>-1</sup> ]	1500	1500	1500	1500	1500
	minimum	$n_{min}$	[min <sup>-1</sup> ]	500	500	500	500	500
	maximum	$n_{max}$	[min <sup>-1</sup> ]	3100	2800	2500	2400	2200
Pressure at outlet	minimum	$p_{1min}$	[bar]	-0.3	-0.3	-0.3	-0.3	-0.3
	maximum	$p_{1max}$	[bar]	180	160	145	130	100
Pressure at inlet	max. continuous	$p_{2n}$	[bar]	250	230	215	200	170
	maximum	$p_{2max}$	[bar]	260	250	235	220	190
	peak	$p_3$	[bar]	270	260	245	230	200
Nominal input flow rate (max.) at $n_n$ and $p_{2n}$		$Q_n$	[dm <sup>3</sup> .min <sup>-1</sup> ]	13.37	16.71	18.38	20.05	25.06
Maximum input flow rate at $n_{max}$ and $p_{2max}$		$Q_{max}$	[dm <sup>3</sup> .min <sup>-1</sup> ]	25.60	29.86	28.16	30.71	35.19
Nominal output power (min.) at $n_n$ and $p_{2n}$		$P_n$	[kW]	4.80	5.30	5.48	5.60	5.72
Maximum output power at $n_{max}$ and $p_{2max}$		$P_{max}$	[kW]	9.94	10.69	9.62	9.87	9.90
Nominal Torque at $n_n$ and $p_{2n}$		$M$	[Nm]	30.38	35.06	35.80	36.62	35.06
Weight		$m$	[kg]	2.00	2.10	2.10	2.20	2.45

External drainage must be used in case of the reversible design.

## FORMULAS USED FOR CALCULATION

Flow rate  
 $Q$

$$Q = \frac{V_g \cdot n}{1000} \cdot \eta_v \quad [\text{dm}^3 \cdot \text{min}^{-1}]$$

$V_g$  [cm<sup>3</sup>] pump displacement  
 $n$  [min<sup>-1</sup>] rotation speed  
 $\eta_v$  [-] volumetric efficiency

Displacement  
 $V_g$

$$V_g = \frac{Q \cdot 1000}{n \cdot \eta_v} \quad [\text{cm}^3]$$

Torque  
 $M_k$

$$M_k = \frac{V_g \cdot p}{20 \cdot \pi \cdot \eta_m} \quad [\text{Nm}]$$

$p$  [bar] required pressure at outlet  
 $\eta_m$  [-] mechanical efficiency

Input power  
 $P$

$$P = \frac{V_g \cdot n \cdot p}{600 \cdot 1000 \cdot \eta_t} \quad [\text{kW}]$$

$\eta_t$  [-] total efficiency

## PUMP EFFICIENCIES

Volumetric efficiency

$\eta_v$

It determines the amount of flow losses. Its value is  $\eta_v = 0,92 \div 0,98$  (depending on rotation speed, viscosity of working liquid and outlet pressure). It can be expressed as follows:

$$\eta_v = \frac{Q_{act.}}{Q_{theor}} \quad [-]$$

$Q_{act.}$  [dm<sup>3</sup> · min<sup>-1</sup>] actual flow rate  
 $Q_{theor}$  [dm<sup>3</sup> · min<sup>-1</sup>] theoretical flow rate

Mechanical efficiency

$\eta_m$

It determines mechanical losses. Its value is about  $\eta_m = 0,85$ . It can be expressed as follows:

$$\eta_m = \frac{M_{theor}}{M_{act.}} \quad [-]$$

$M_{act.}$  [Nm] actual torque  
 $M_{theor}$  [Nm] theoretical torque

Total efficiency

$\eta_t$

It is defined as product of  $\eta_n$  and  $\eta_m$  and determines difference between theoretical and actual required input power:

$$\eta_t = \eta_v \cdot \eta_m = \frac{P_{theor}}{P_{act.}} \quad [-]$$

$P_{act.}$  [kW] actual input power  
 $P_{theor}$  [kW] theoretical input power

## WORKING LIQUID

- Mineral oils for hydraulic drives
- Hydraulic liquids based on plant oils suitable for hydraulic drives

### Liquid temperature

- $t = -20 \div +80$  [°C]  
when used with FKM (Viton) seal up to 120 [°C]

### Cinematic viscosity

- Recommended (during continuous operation):  $\nu = 20 \div 80 \cdot 10^{-6} [\text{m}^2 \cdot \text{s}^{-1}]$
- Maximum (cold starting, at viscosity  $>1000$ , operating pressure  $<10$  bar is permissible, speed  $<1500 \cdot \text{min}^{-1}$ ):  $\nu = 1200 \cdot 10^{-6} [\text{m}^2 \cdot \text{s}^{-1}]$
- Minimum (operating mode at  $10 \cdot 10^{-6}$  up  $20 \cdot 10^{-6}$  should be consulted with manufacturer):  $\nu = 10 \cdot 10^{-6} [\text{m}^2 \cdot \text{s}^{-1}]$

### Filtration coefficient $\beta_\alpha$

$\beta_{25} 75 \geq$  (for pressure  $p_2 < 200$  bar)  
 $\beta_{10} 75 \geq$  (for pressure  $p_2 > 200$  bar)

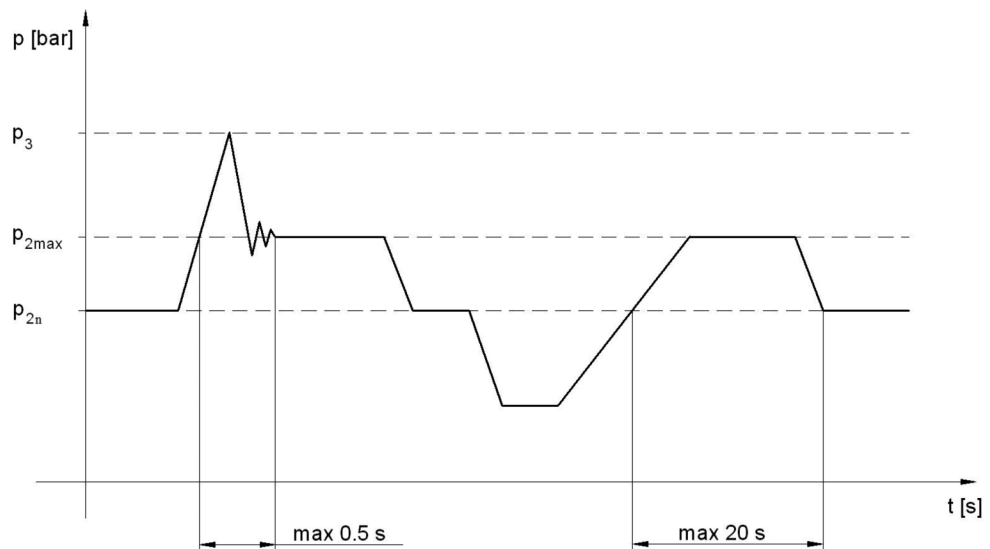
### Liquid contamination class according to ISO 4406

21/18/15 (for pressure  $p_2 < 200$  bar)  
 20/17/14 (for pressure  $p_2 > 200$  bar)

### Liquid contamination class according to NAS 1638

10 (for pressure  $p_2 < 200$  bar)  
 8 (for pressure  $p_2 > 200$  bar)

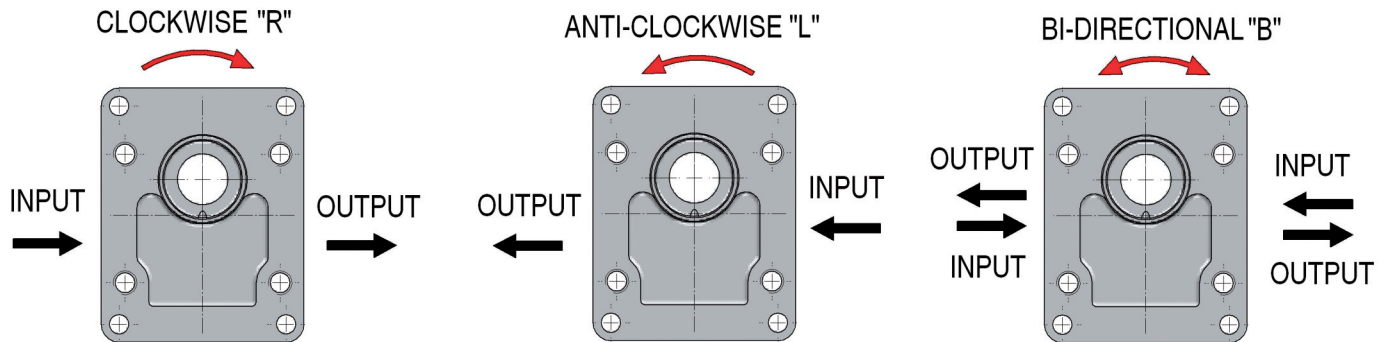
## PRESSURE LOAD



- $p_{2n}$  **max. contin. pressure** Max. working pressure, at which the pump can be operated without time limitation.
- $p_{2max}$  **max. pressure** Maximum pressure permissible for a short time, max. 20s.
- $p_3$  **peak pressure** Short-time pressure (fractions of a second) arising in case of a sudden change of the operating mode; any excess of this pressure during operation is impermissible.

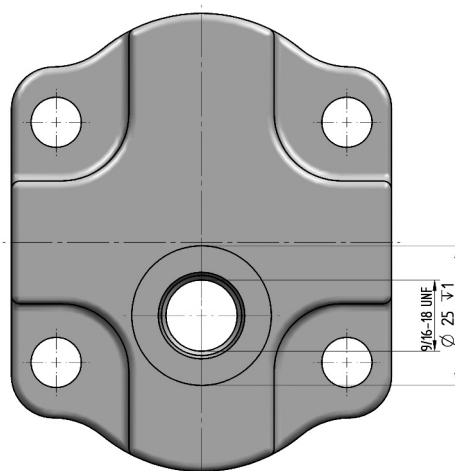
## DIRECTION OF ROTATION

- Determine direction of rotation by looking at the drive shaft. The motor can only be used in the specified direction of rotation.

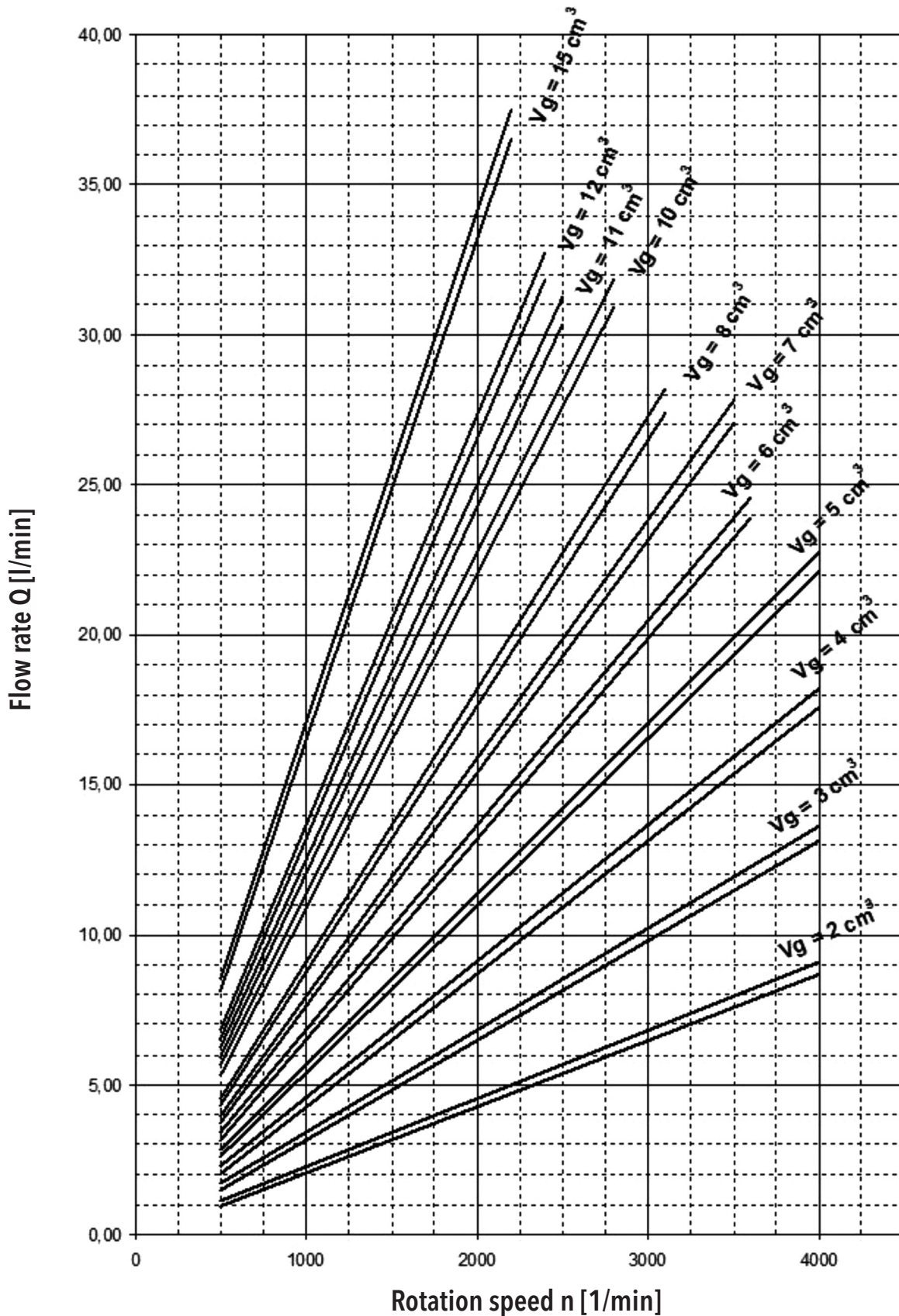


## REVERSIBLE DESIGN

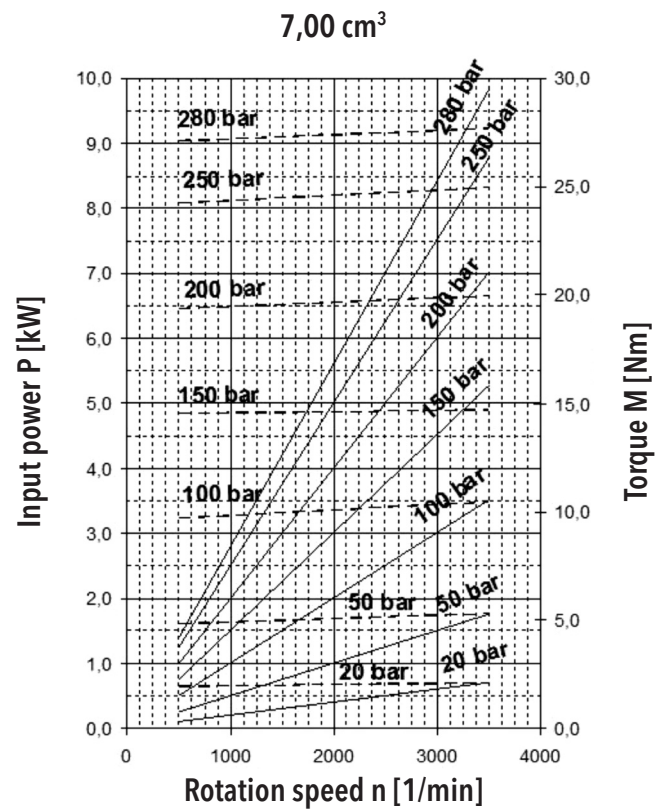
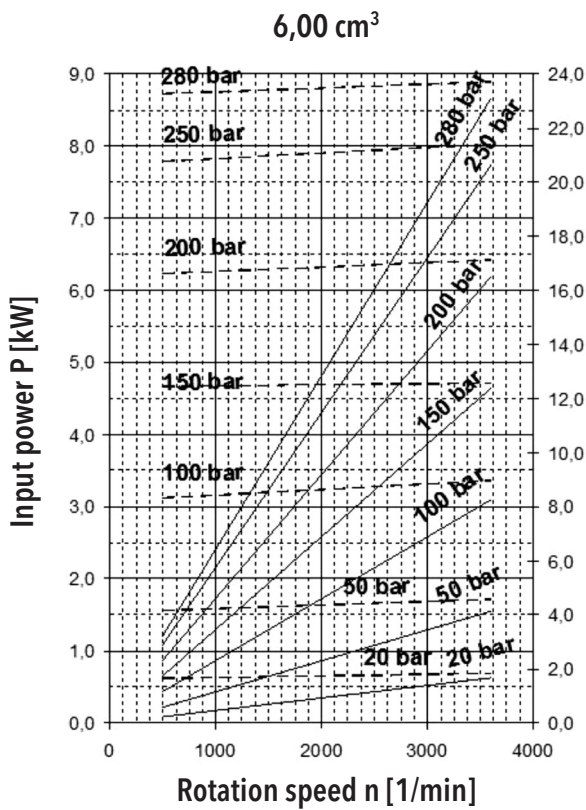
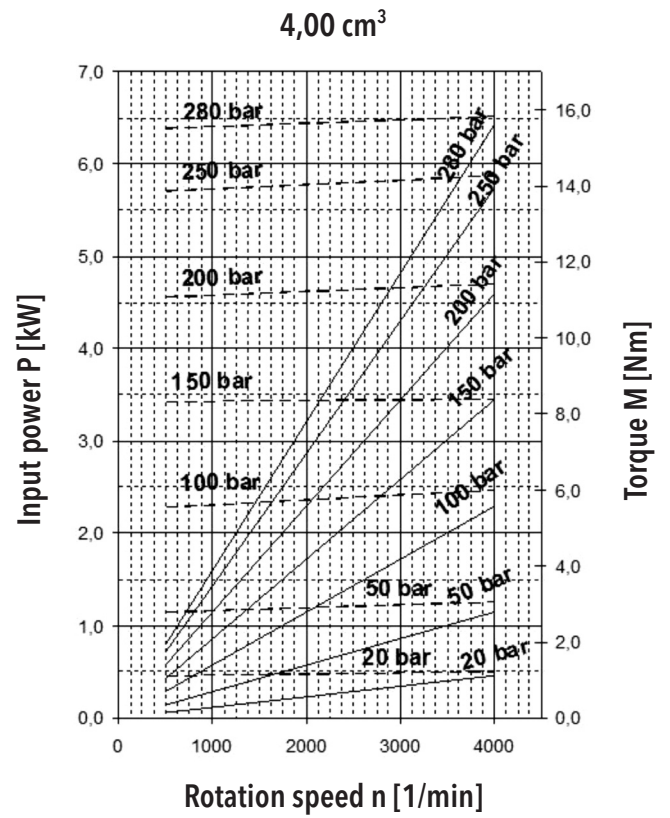
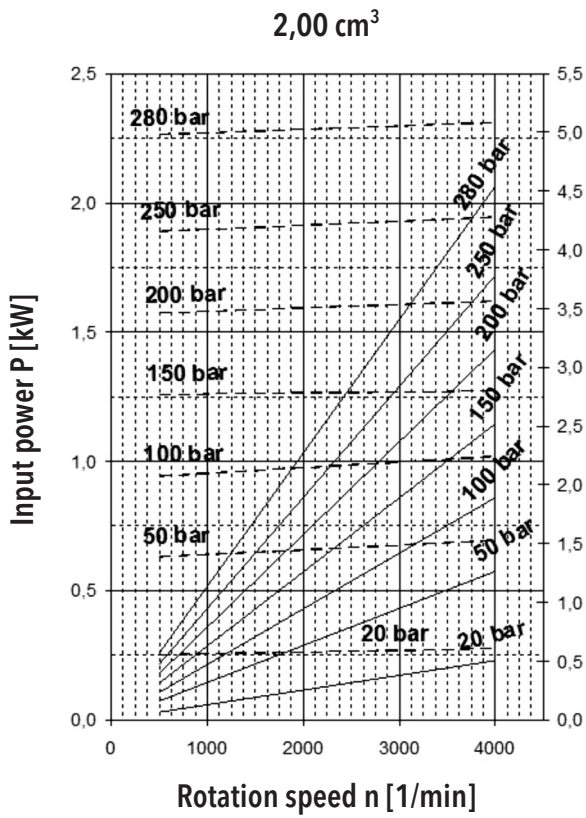
- The motors with the possibility of bidirectional rotation have a different internal arrangement requiring drainage. Two types are used - internal and external. The internal drainage is always interconnected with the outlet by means of valves. The external drainage is solved by an orifice located in the cover opposite the driven gear.

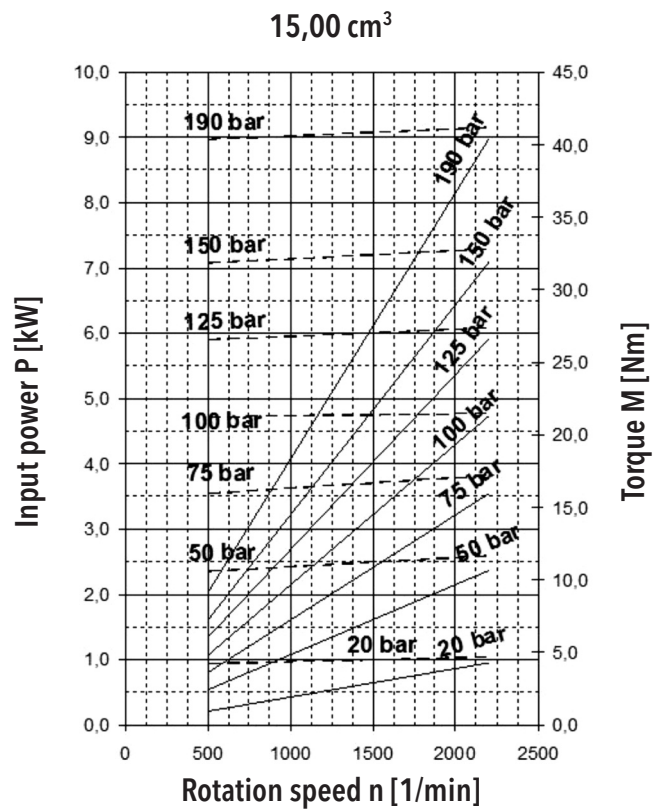
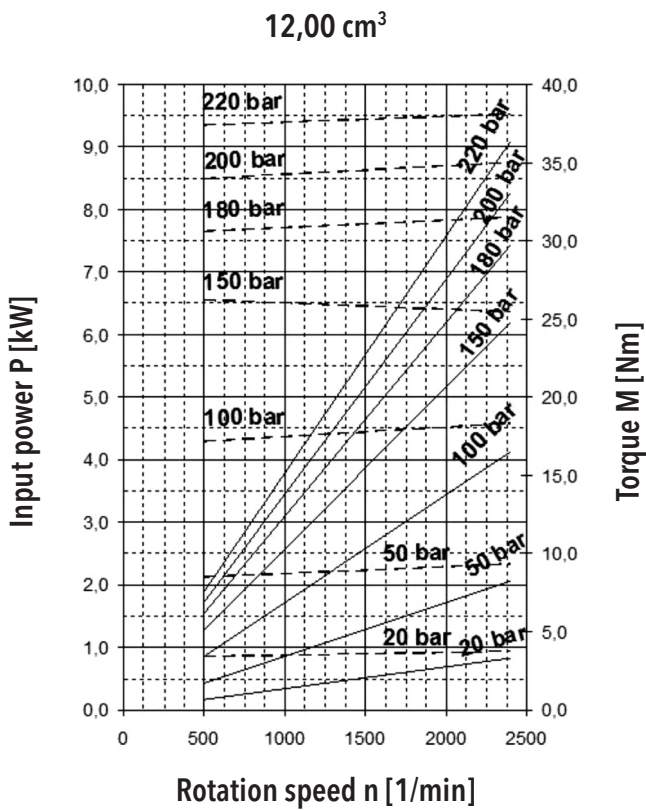
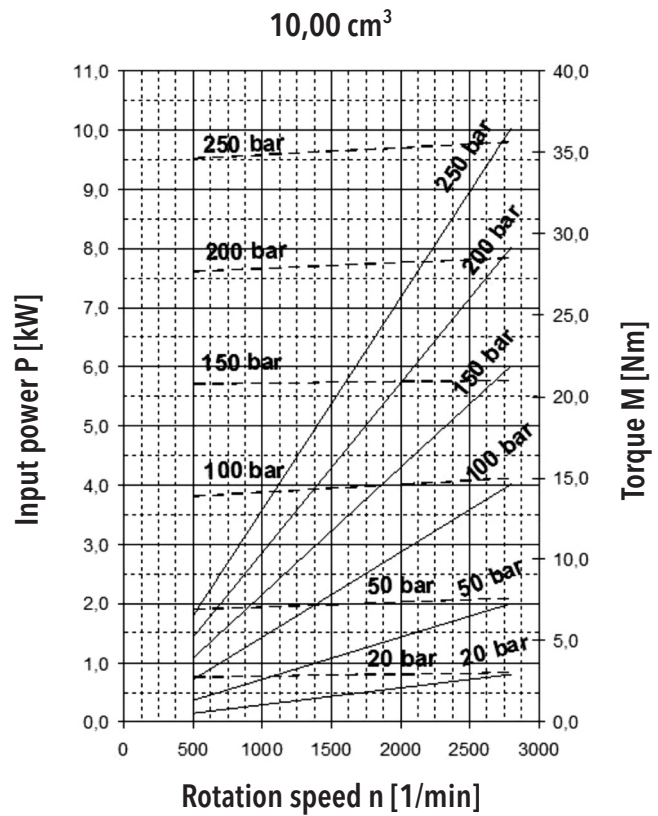
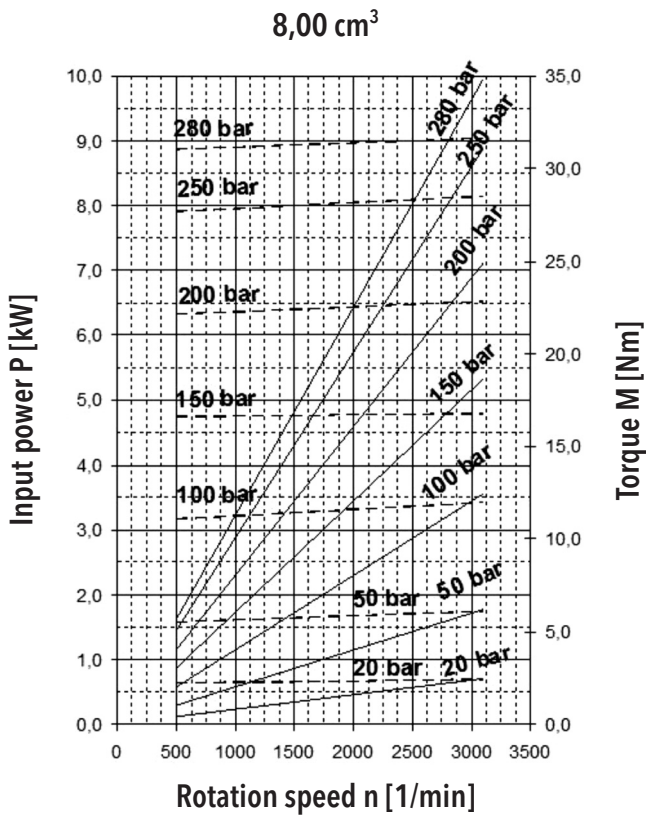


## JM FLOW RATE AND POWER CURVES



Above curves apply to ISO Vg 46 oil at temperature  $t = 45^{\circ}\text{C}$ .










## ORDER KEY




**JM - 2 R - S01 D03 - S G04 G03 - V . 001**

Code	Type
JM	JM Series Gear Motor
JMK	JM Series Gear Motor short version

Code	Displacement [cm <sup>3</sup> ]
2	2
3	3
4	4
5	5
6	6
7	7
8	8
9	9
10	10
11	11
12	12
13	13
14	14
15	15
18	18
XX	Other displacements on request














Code	Direction of rotation
R	Clockwise
L	Anti-clockwise
B	Bi-directional















Code	Flange design
R03	 Square flange, centre ring Ø80
R05	 Rectangular flange, centre ring Ø36,5
S01	 SAE AA, centre ring Ø50,8
S02	 SAE A, centre ring Ø82,5
F01	 ISO, centre ring Ø45,25
Z	Special desing

Code	Location of inlets and outlets
S	 Side (in the body)
R	 Axial (in the cover)
C	 Combination

Code	Special arrangements
-	No special arrangements
001	With front-end bearing
004	Without shaft seal

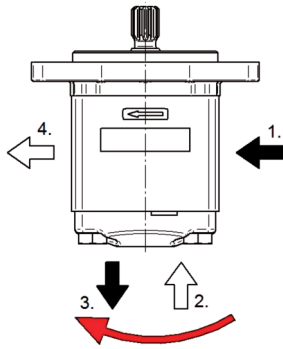
Code	Seal material
N	NBR
V	FKM (VITON)
H	HNBR

Code	Drive shaft desing
C05	 Cone 1:8 Key width 3
C06	 Cone 1:8 Key width 2,4
D02	 Spline 20/40 - 30° SAE 9T; l=9
D03	 Spline 20/40 - 30° SAE 9T; l=27
D04	 Spline 16/32 - 30° SAE 9T; l=32
D05	 Spline 16/32 - 30° SAE 8T; l=32
K05	 Cross coupling 4,37
K06	 Cross coupling 5
V06	 Cylindric Ø12 Key 3; M10; l=31,5
V07	 Cylindric Ø12,7 Key 3,18; l=27
V08	 Cylindric Ø12,7 Key 3,18; l=38,2
V09	 Cylindric Ø15,88 Key 3,97; l=32
V10	 Cylindric Ø16 1/4" - 20UNC THD
Z	Special desing

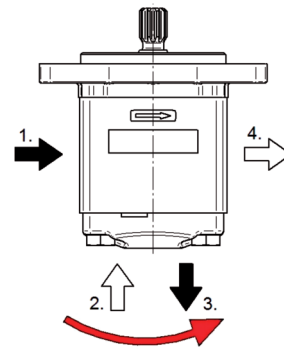
Code	Liquid inlet and outlet connection shape
M03	 Thread M 14x1,5
M05	 Thread M 18x1,5
M07	 Thread M 22x1,5
G01	 Thread BSP G1/4
G02	 Thread BSP G3/8
G03	 Thread BSP G1/2
G04	 Thread BSP G3/4
U02	 Thread 9/16-18 UNF-2B
U03	 Thread 3/4-16 UNF-2B
U04	 Thread 7/8-14 UNF-2B
R02	 Thread 3/8-18NPT
R03	 Thread 1/2-14NPT
H03	 Fitting Ø8; Square 4xM6 Ø30
H04	 Fitting Ø12; Square 4xM6 Ø30
H05	Fitting Ø15; Square 4xM6 Ø35
H06	Fitting Ø20; Square 4xM6 Ø40
S02	Fitting Square 4xM8/25 15x25, 15
Z	Special desing

An example of designation for the JM clockwise motor with displacement of 2 cm<sup>3</sup>, Rectangular flange with centre ring Ø 50.8, Cylindric Ø12, BSP side inlets, FKM seal and with front-end bearing: **JM-2R-R03V06-SG04G03-V.001**

Note: In case of combination inlets, with the code „C” is respected following sequence of inlets and outlets:



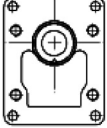
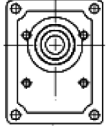
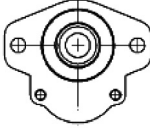
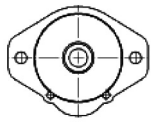



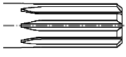
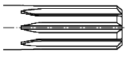
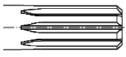
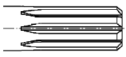

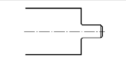
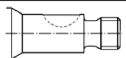
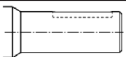
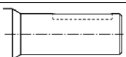
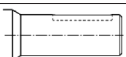
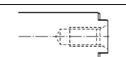
For clockwise and reverse gear motor,  
in direction clockwise



For anti-clockwise gear motor,  
in direction anti-clockwise

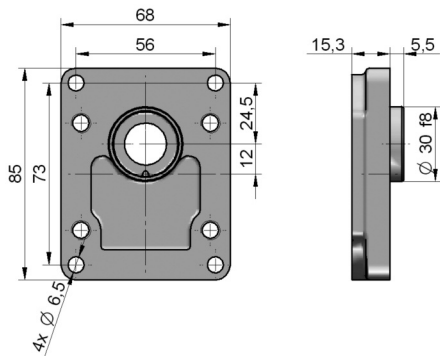
For. ex....: JM-12R-S01D03-CG03 G03 G04 G04 -N  
1. 2. 3. 4.

## COMBINATIONS OF FLANGES AND SHAFTS

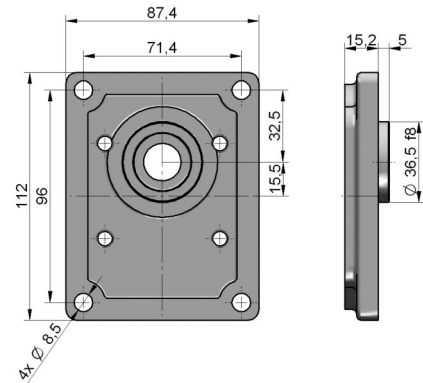
		FLANGE DESIGN				
		R03	R05	S01	S02	F01
						
<b>DRIVE SHAFT</b>	C05		●	●	●	
	C06		●	●		●
	D02				●	●
	D03				●	●
	D04				●	●
	D05				●	●
	K05					●
	K06				●	
	V06		●			
	V07				●	
	V08		●		●	●
	V09			●	●	●
V10					●	

## FLANGES DESIGN

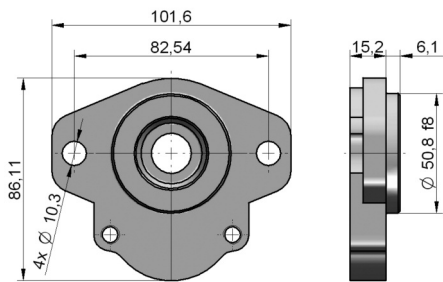
**R03:**



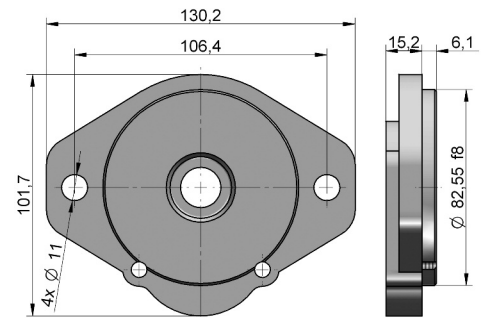
**R05:**



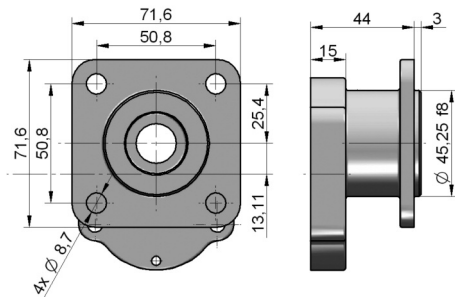
**S01:**



**S02:**

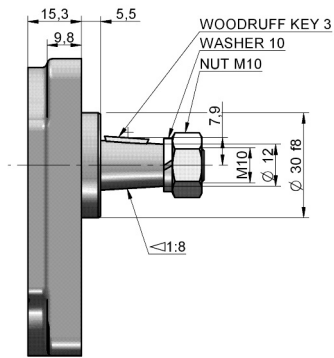


**F01:**

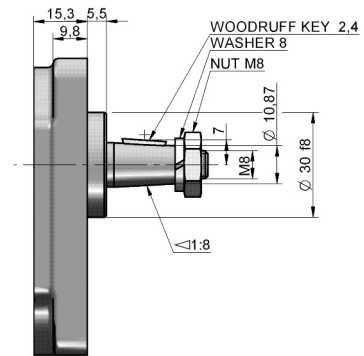


## DRIVE SHAFTS

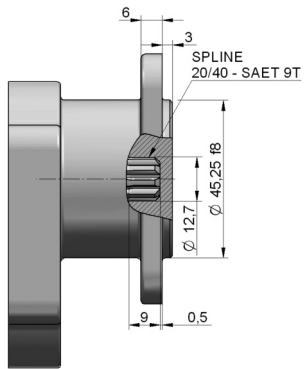
**C05:**



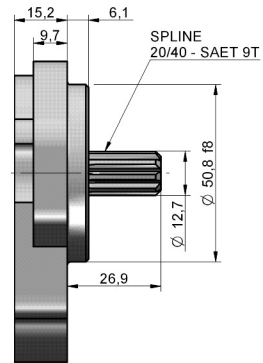
**C06:**



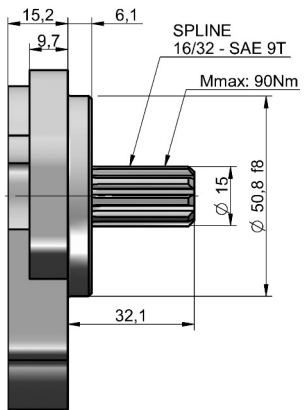
**D02:**



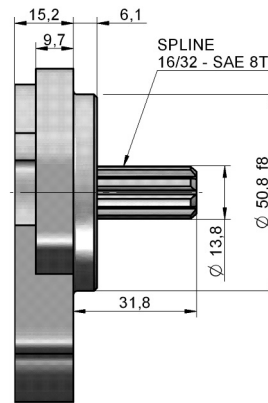
**D03:**



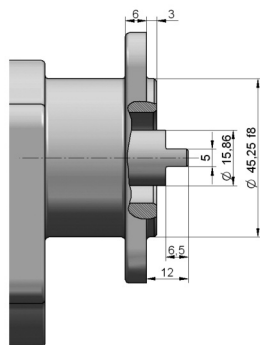
**D04:**



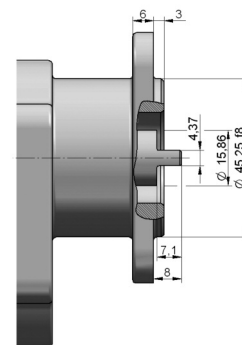
**D05:**



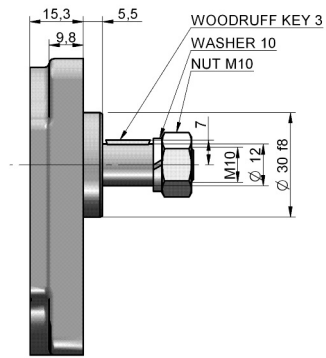
**K05:**



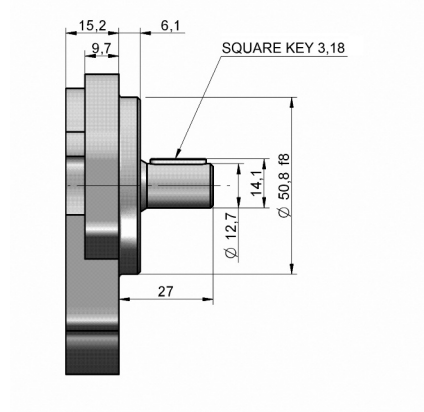
**K06:**



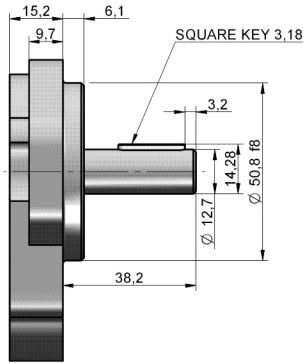
V06:



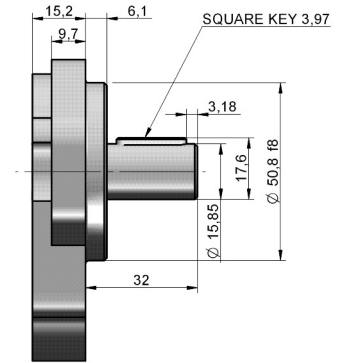
V07:



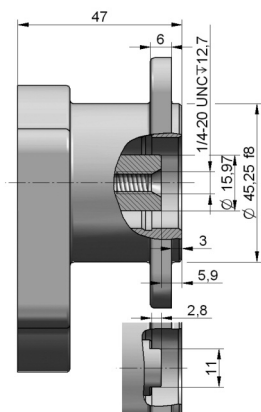
V08:



V09:

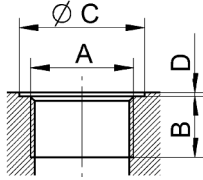


V10:



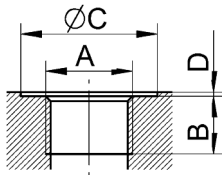
## LIQUID INLET AND OUTLET CONNECTION

### Metric thread according to ISO 6149



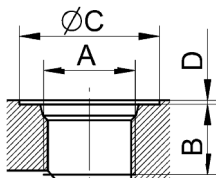
Code	A	B	C	D
M03	M 14 x 1.5	13	22	1
M05	M 18 x 1.5	13	24	1
M07	M 22 x 1.5	14	28	1

### BSPP pipe thread according to ISO 228-1



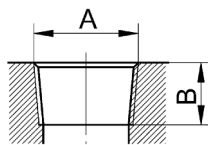
Code	A	B	C	D
G01	G 1/4	12	18	1
G02	G 3/8	13	24	1
G03	G 1/2	14	33	1
G04	G 3/4	16	39	1

### UNF thread according to SAE



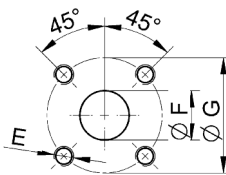
Code	A	B	C	D
U02	9/16 - 18 UNF	13	25	1
U03	3/4 - 16 UNF	15	30	1
U04	7/8 - 14 UNF	17	34	1

### Tapered thread NPT



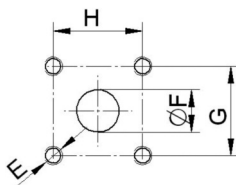
Code	A	B
R02	3/8 - 18 NPT	16.0
R03	1/2 - 14 NPT	20.8

### Flanged fittings according to DIN 8901/8902



Code	A	B	C
H03	M6	8	30
H04	M6	12	30
H05	M6	15	35
H06	M6	20	40

### Flanged fittings ISO

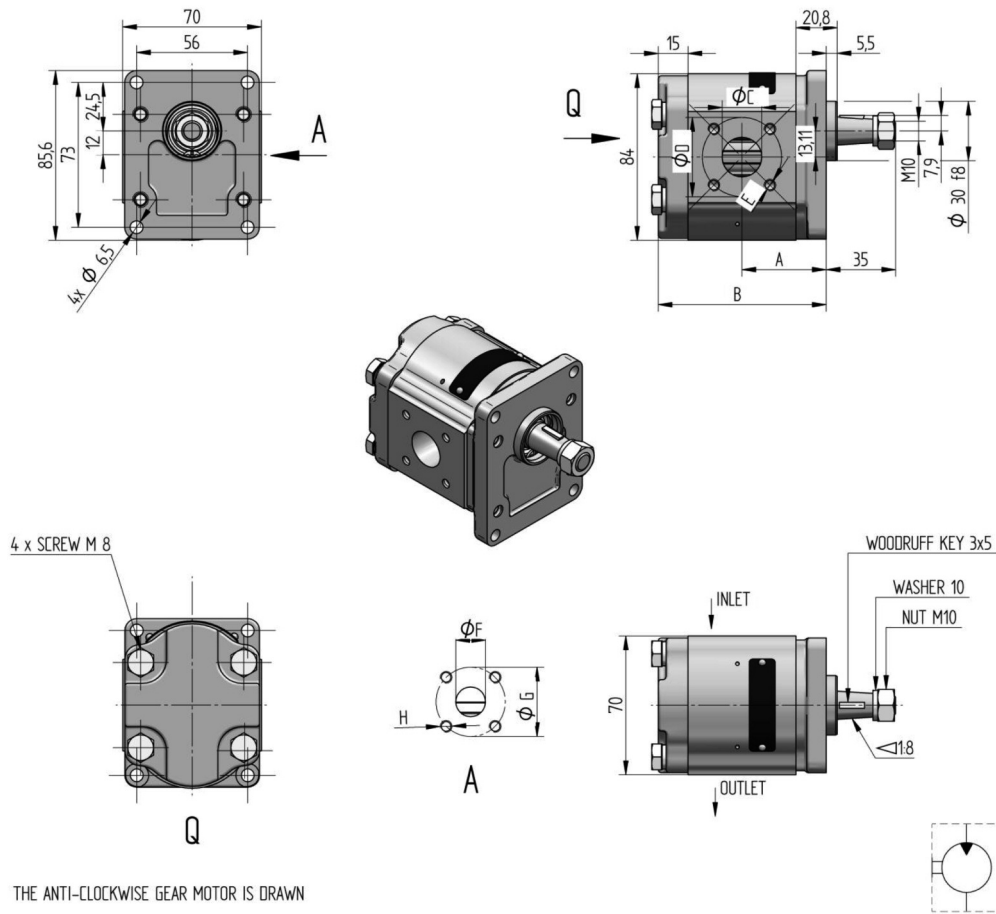


Code	E	F	G	H
S02	1/4 UNC	14.2	25.15	25.15
S03	M8	14.2	25.15	25.15

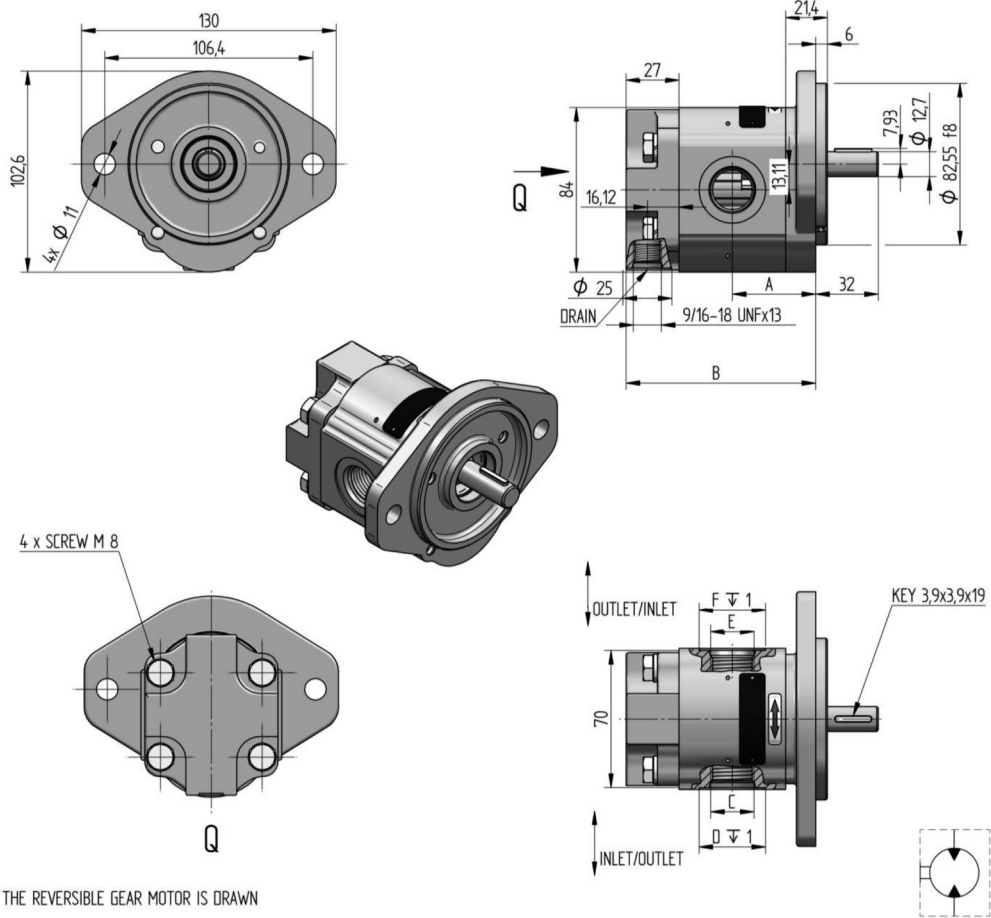
### Drains

Code	A	B	C	D
U01	7/16-20 UNF 2B	13	21	1
G01	G 1/4	12	18	1

## CATALOGUE SHETS OF JM SERIES BASIC DESIGNS

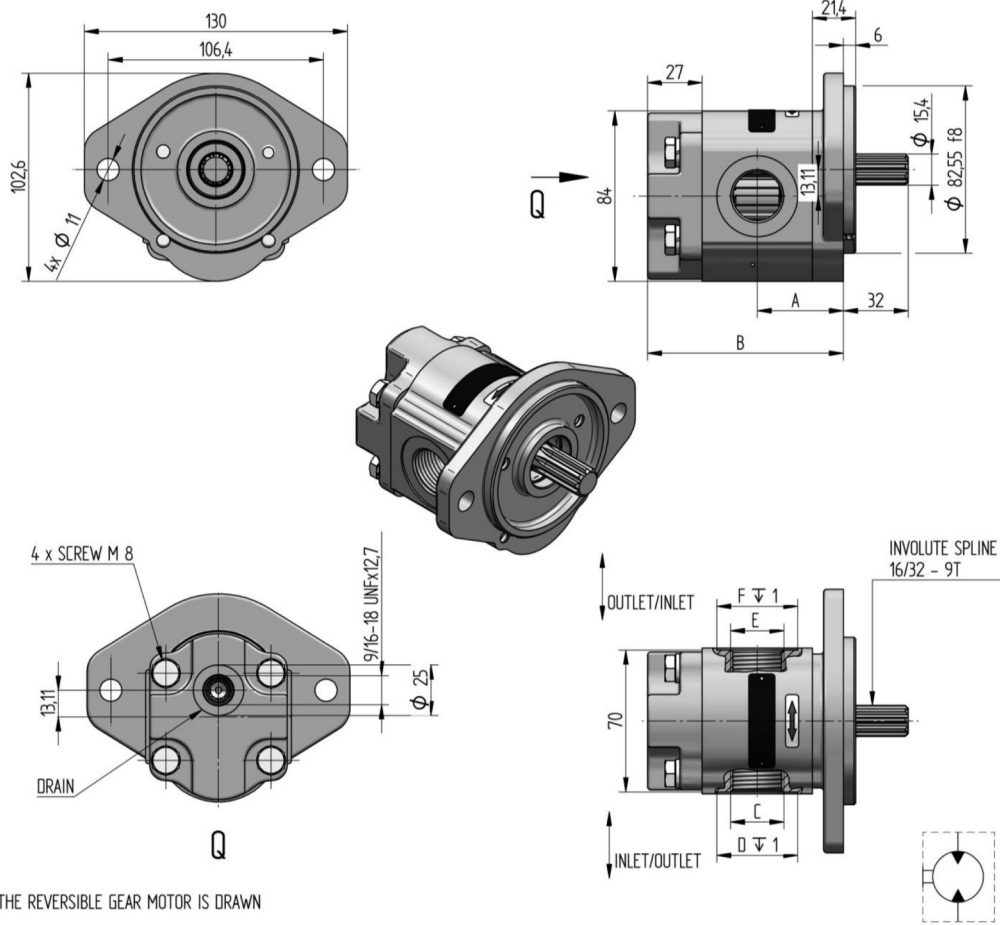


Order key	purch. code	direct. of rot.	displacement [cm <sup>3</sup> /1]	nom. press. [bar]	speed MIN. [min <sup>-1</sup> ]	speed MAX. [min <sup>-1</sup> ]	dimension							
							A [mm]	B [mm]	C [mm]	D [mm]	E [mm]	F [mm]	G [mm]	H [mm]
JM-15R-R03C05-S H06H05-N		R	15	190	500	2200	51.86	103.42	20	40	M6x13	15	35	M6x13
JM-15L-R03C05-S H06H05-N		L												
JM-12R-R03C05-S H06H05-N		R	12	220	500	2400	47.88	95.46	20	40	M6x13	15	35	M6x13
JM-12L-R03C05-S H06H05-N		L												
JM-11R-R03C05-S H06H05-N		R	11	235	500	2500	46.55	92.80	20	40	M6x13	15	35	M6x13
JM-11L-R03C05-S H06H05-N		L												
JM-10R-R03C05-S H06H05-N		R	10	250	500	2800	45.21	90.12	20	40	M6x13	15	35	M6x13
JM-10L-R03C05-S H06H05-N		L												
JM-8R-R03C05-S H06H05-N		R	8	280	500	3100	42.54	84.79	20	40	M6x13	15	35	M6x13
JM-8L-R03C05-S H06H05-N		L												
JM-7R-R03C05-S H06H05-N		R	7	280	500	3500	41.21	82.12	20	40	M6x13	15	35	M6x13
JM-7L-R03C05-S H06H05-N		L												
JM-6R-R03C05-S H06H05-N		R	6	280	500	3600	39.87	79.44	20	40	M6x13	15	35	M6x13
JM-6L-R03C05-S H06H05-N		L												
JM-5R-R03C05-S H06H05-N		R	5	280	500	4000	38.54	76.78	20	40	M6x13	15	35	M6x13
JM-5L-R03C05-S H06H05-N		L												
JM-4R-R03C05-S H06H05-N		R	4	280	500	4000	37.20	74.11	20	40	M6x13	15	35	M6x13
JM-4L-R03C05-S H06H05-N		L												
JM-3R-R03C05-S H06H05-N		R	3	280	500	4000	35.87	71.44	20	40	M6x13	15	35	M6x13
JM-3L-R03C05-S H06H05-N		L												
JM-2R-R03C05-S H06H05-N		R	2	280	500	4000	34.53	68.76	20	40	M6x13	15	35	M6x13
JM-2L-R03C05-S H06H05-N		L												



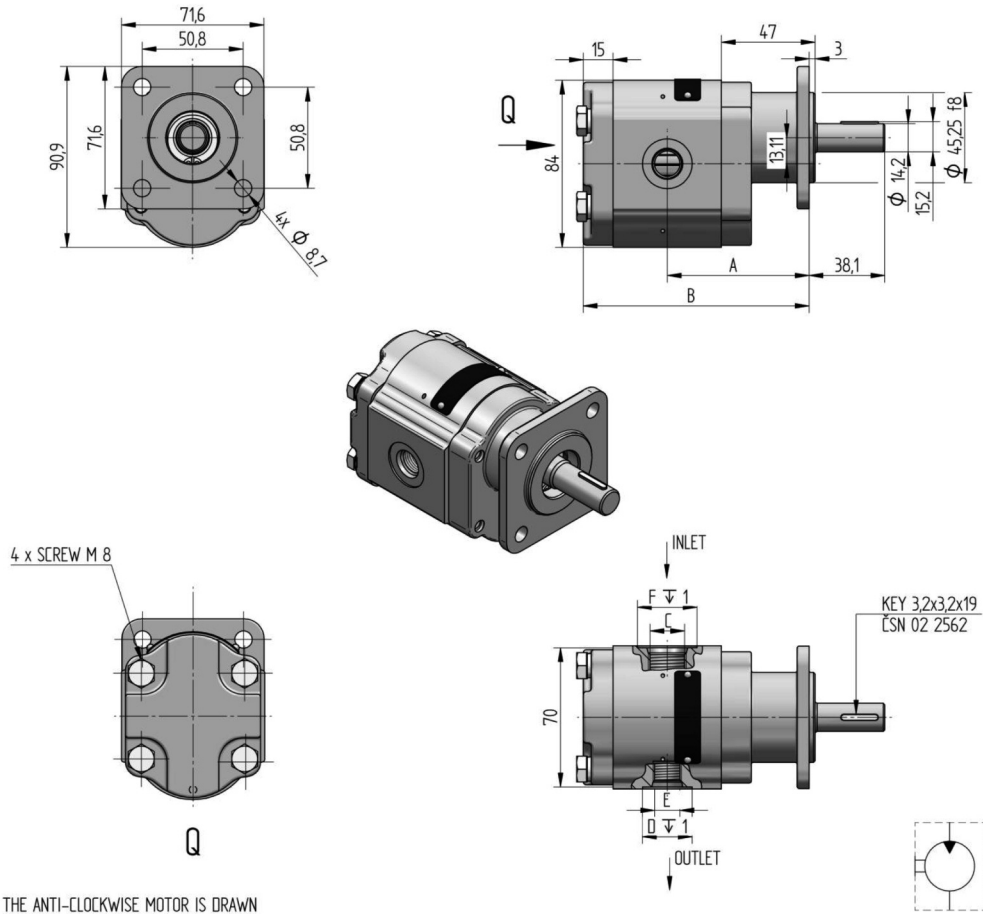
THE REVERSIBLE GEAR MOTOR IS DRAWN

Order key	purch. code	direct. of rot.	displacement [cm <sup>3</sup> /1]	nom. press. [bar]	speed MIN. [min <sup>-1</sup> ]	speed MAX. [min <sup>-1</sup> ]	dimension					
							A [mm]	B [mm]	C [mm]	D [mm]	E [mm]	F [mm]
JM-15B- S02V08-SU04U04-N		B	15	190	500	2200	80,56	132,12	7/8-14UNFx17	∅ 34	7/8-14UNFx17	∅ 30
JM-12B- S02V08-SU04U04-N		B	12	220	500	2400	76,58	124,16	7/8-14UNFx17	∅ 34	7/8-14UNFx17	∅ 30
JM-11B- S02V08-SU04U04-N		B	11	235	500	2500	75,25	121,50	7/8-14UNFx17	∅ 34	7/8-14UNFx17	∅ 30
JM-10B- S02V08-SU04U04-N		B	10	250	500	2800	73,91	118,82	7/8-14UNFx17	∅ 34	7/8-14UNFx17	∅ 30
JM-8B- S02V08-SU04U04-N		B	8	280	500	3100	71,24	113,49	7/8-14UNFx17	∅ 34	7/8-14UNFx17	∅ 30
JM-7B- S02V08-SU04U04-N		B	7	280	500	3500	69,91	110,82	7/8-14UNFx17	∅ 34	7/8-14UNFx17	∅ 30
JM-6B- S02V08-SU04U04-N		B	6	280	500	3600	68,57	108,14	7/8-14UNFx17	∅ 34	7/8-14UNFx17	∅ 30
JM-5B- S02V08-SU04U04-N		B	5	280	500	4000	67,24	105,48	7/8-14UNFx17	∅ 34	7/8-14UNFx17	∅ 30
JM-4B- S02V08-SU04U04-N		B	4	280	500	4000	65,90	102,81	7/8-14UNFx17	∅ 34	7/8-14UNFx17	∅ 30
JM-3B- S02V08-SU04U04-N		B	3	280	500	4000	64,57	100,14	7/8-14UNFx17	∅ 34	7/8-14UNFx17	∅ 30
JM-2B- S02V08-SU04U04-N		B	2	280	500	4000	63,23	97,46	7/8-14UNFx17	∅ 34	7/8-14UNFx17	∅ 30



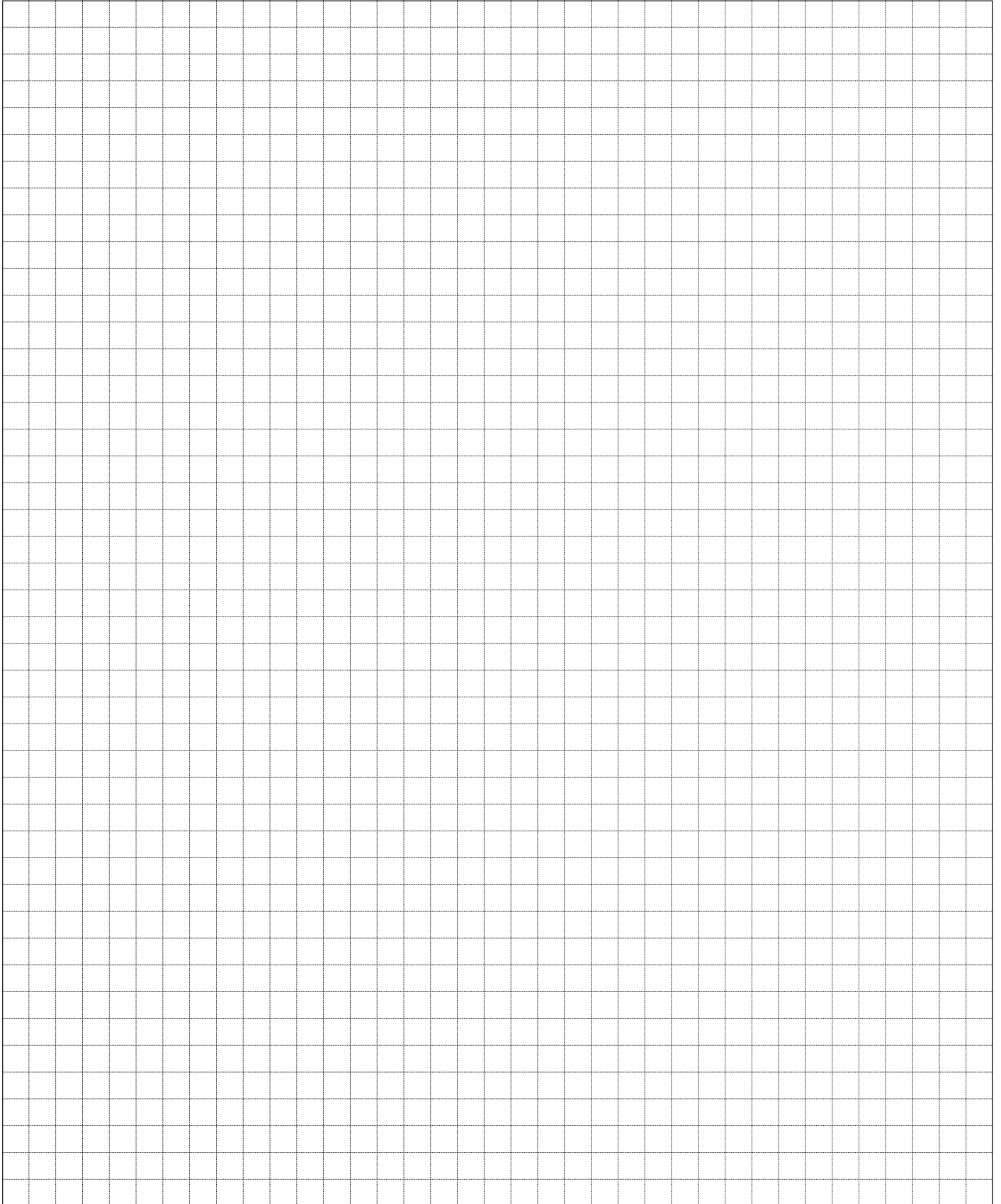
THE REVERSIBLE GEAR MOTOR IS DRAWN

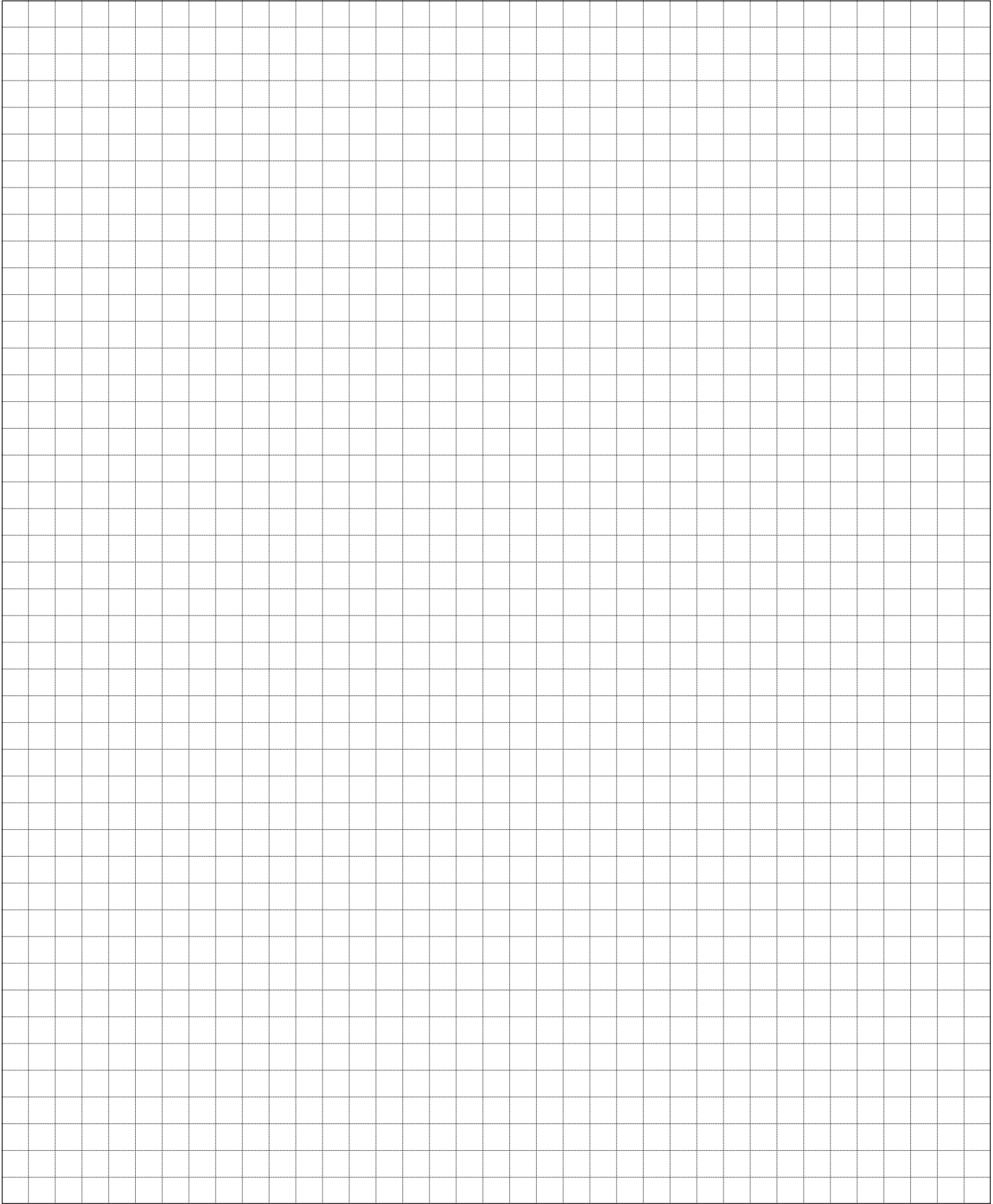
Order key	purch. code	direct. of rot.	displacement [cm <sup>3</sup> /1]	nom. press. [bar]	speed MIN. [min <sup>-1</sup> ]	speed MAX. [min <sup>-1</sup> ]	dimension					
							A [mm]	B [mm]	C [mm]	D [mm]	E [mm]	F [mm]
JM-15B- S02D04-S G04G04-N		B	15	190	500	2200	80,56	132,12	G 3/4 x 16	∅ 39	G 3/4 x 16	∅ 39
JM-12B- S02D04-S G04G04-N		B	12	220	500	2400	76,58	124,16	G 3/4 x 16	∅ 39	G 3/4 x 16	∅ 39
JM-11B- S02D04-S G04G04-N		B	11	235	500	2500	75,25	121,50	G 3/4 x 16	∅ 39	G 3/4 x 16	∅ 39
JM-10B- S02D04-S G04G04-N		B	10	250	500	2800	73,91	118,82	G 3/4 x 16	∅ 39	G 3/4 x 16	∅ 39
JM-8B- S02D04-S G04G04-N		B	8	280	500	3100	71,24	113,49	G 3/4 x 16	∅ 39	G 3/4 x 16	∅ 39
JM-7B- S02D04-S G04G04-N		B	7	280	500	3500	69,91	110,82	G 3/4 x 16	∅ 39	G 3/4 x 16	∅ 39
JM-6B- S02D04-S G04G04-N		B	6	280	500	3600	68,57	108,14	G 3/4 x 16	∅ 39	G 3/4 x 16	∅ 39
JM-5B- S02D04-S G04G04-N		B	5	280	500	4000	67,24	105,48	G 3/4 x 16	∅ 39	G 3/4 x 16	∅ 39
JM-4B- S02D04-S G04G04-N		B	4	280	500	4000	65,90	102,81	G 3/4 x 16	∅ 39	G 3/4 x 16	∅ 39
JM-3B- S02D04-S G04G04-N		B	3	280	500	4000	64,57	100,14	G 3/4 x 16	∅ 39	G 3/4 x 16	∅ 39
JM-2B- S02D04-S G04G04-N		B	2	280	500	4000	63,23	97,46	G 3/4 x 16	∅ 39	G 3/4 x 16	∅ 39

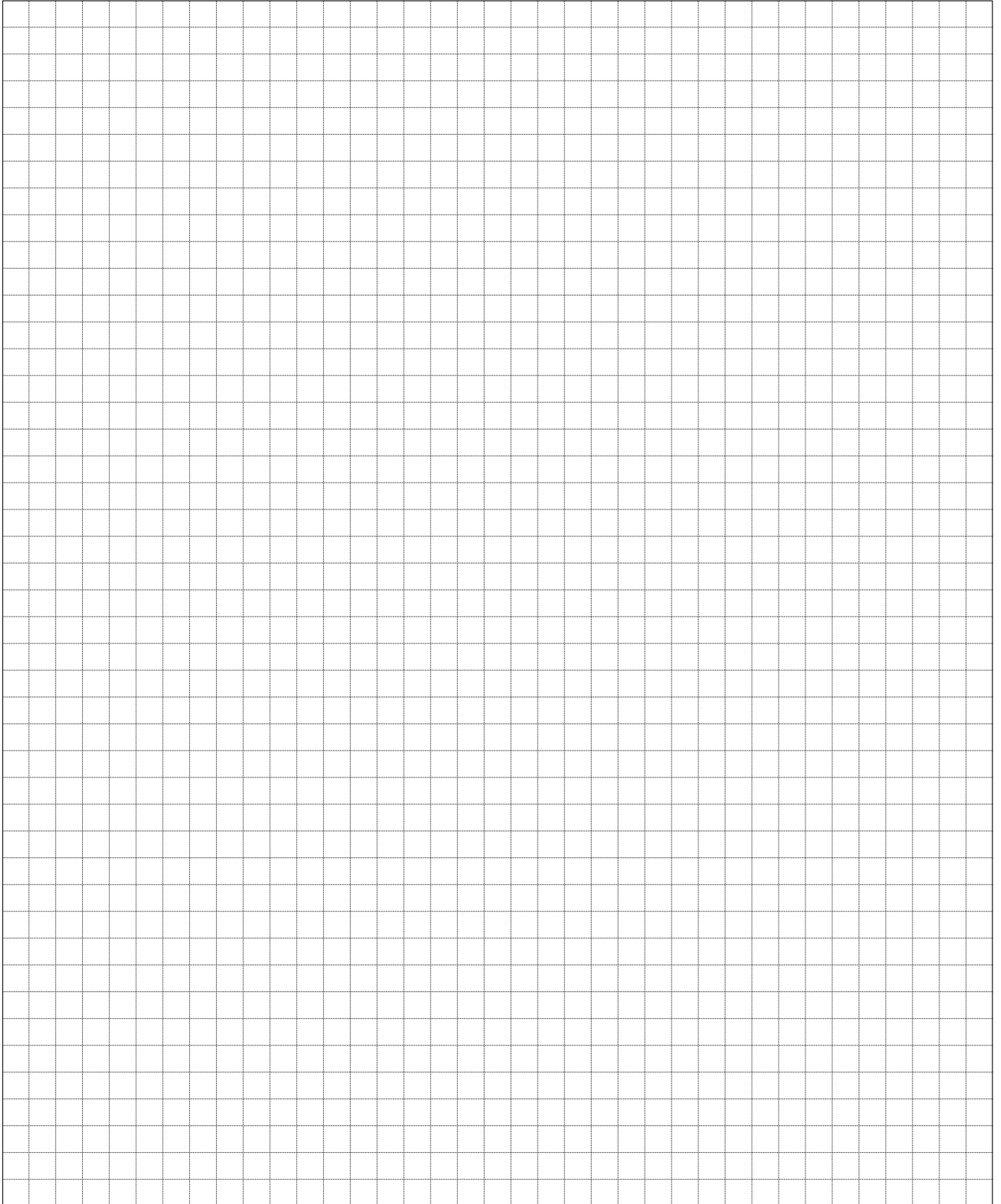


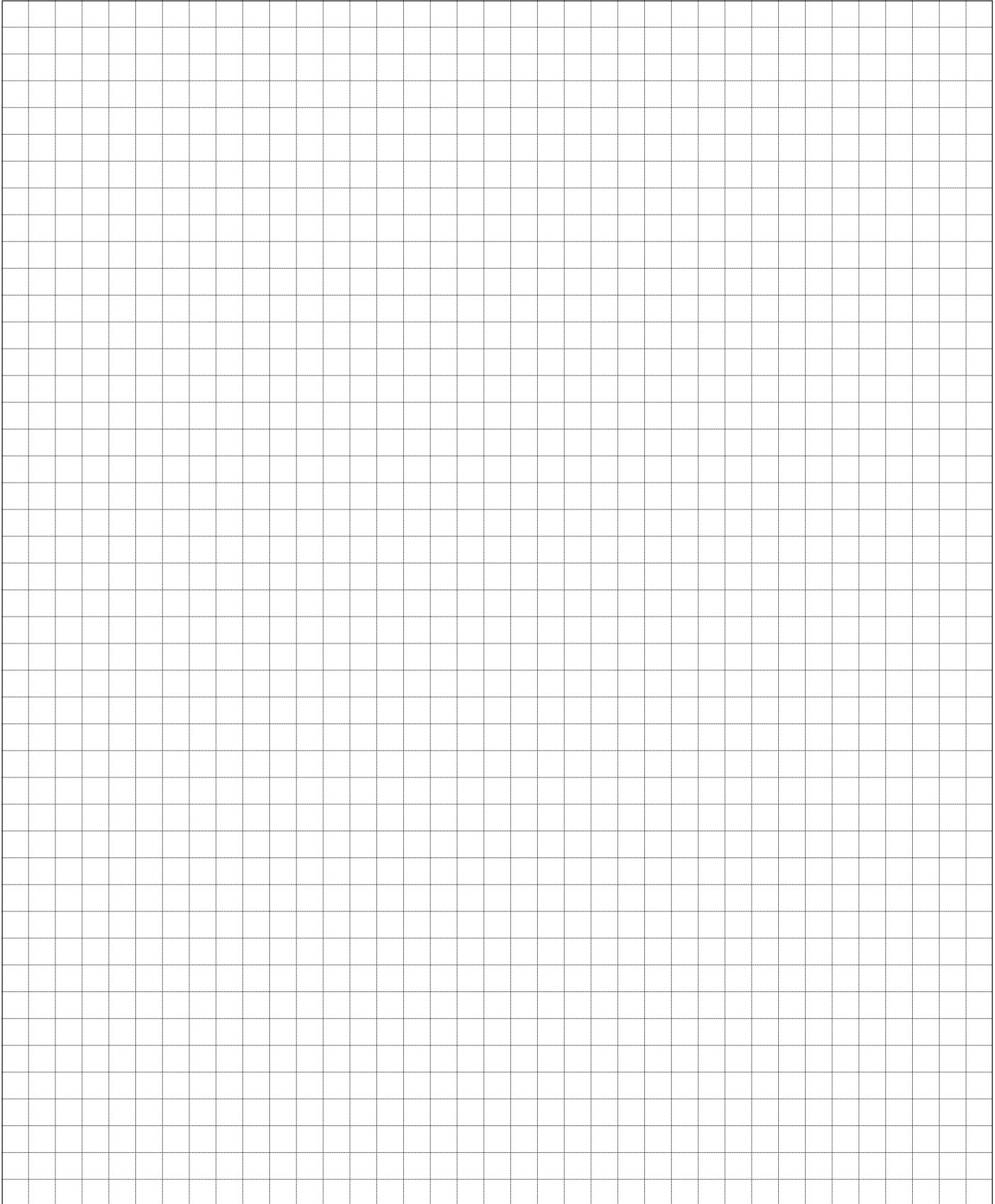
THE ANTI-CLOCKWISE MOTOR IS DRAWN

Order key	purch. code	direct. of rot.	displacement [cm <sup>3</sup> /1]	nom. press. [bar]	speed MIN. [min <sup>-1</sup> ]	speed MAX. [min <sup>-1</sup> ]	dimension					
							A [mm]	B [mm]	C [mm]	D [mm]	E [mm]	F [mm]
JM-15R- F01V08-S U03U02-N		R	15	190	500	2200	80.56	132.12	3/4-16UNFx15	Ø 30	9/16-18UNFx13	Ø 25
JM-15L- F01V08-S U03U02-N		L										
JM-12R- F01V08-S U03U02-N		R	12	220	500	2400	76.58	124.16	3/4-16UNFx15	Ø 30	9/16-18UNFx13	Ø 25
JM-12L- F01V08-S U03U02-N		L										
JM-11R- F01V08-S U03U02-N		R	11	235	500	2500	75.25	121.50	3/4-16UNFx15	Ø 30	9/16-18UNFx13	Ø 25
JM-11L- F01V08-S U03U02-N		L										
JM-10R- F01V08-S U03U02-N		R	10	250	500	2800	73.91	118.82	3/4-16UNFx15	Ø 30	9/16-18UNFx13	Ø 25
JM-10L- F01V08-S U03U02-N		L										
JM-8R- F01V08-S U03U02-N		R	8	280	500	3100	71.24	113.49	3/4-16UNFx15	Ø 30	9/16-18UNFx13	Ø 25
JM-8L- F01V08-S U03U02-N		L										
JM-7R- F01V08-S U03U02-N		R	7	280	500	3500	69.91	110.82	3/4-16UNFx15	Ø 30	9/16-18UNFx13	Ø 25
JM-7L- F01V08-S U03U02-N		L										
JM-6R- F01V08-S U03U02-N		R	6	280	500	3600	68.57	108.14	3/4-16UNFx15	Ø 30	9/16-18UNFx13	Ø 25
JM-6L- F01V08-S U03U02-N		L										
JM-5R- F01V08-S U03U02-N		R	5	280	500	4000	67.24	105.48	3/4-16UNFx15	Ø 30	9/16-18UNFx13	Ø 25
JM-5L- F01V08-S U03U02-N		L										
JM-4R- F01V08-S U03U02-N		R	4	280	500	4000	65.90	102.81	3/4-16UNFx15	Ø 30	9/16-18UNFx13	Ø 25
JM-4L- F01V08-S U03U02-N		L										
JM-3R- F01V08-S U03U02-N		R	3	280	500	4000	64.57	100.14	3/4-16UNFx15	Ø 30	9/16-18UNFx13	Ø 25
JM-3L- F01V08-S U03U02-N		L										
JM-2R- F01V08-S U03U02-N		R	2	280	500	4000	63.23	97.46	3/4-16UNFx15	Ø 30	9/16-18UNFx13	Ø 25
JM-2L- F01V08-S U03U02-N		L										











**jihostroj**  
AERO TECHNOLOGY & HYDRAULICS

**JIHOSTROJ a.s.**  
Budějovická 148  
CZ 382 32 Velešín  
Czech Republic  
tel.: +420 380 340 511  
fax: +420 380 340 612  
e-mail: mailbox@jihostroj.cz  
http: //www.jihostroj.com

GPS 48°49'51.748" N 14°27'40.770" E

